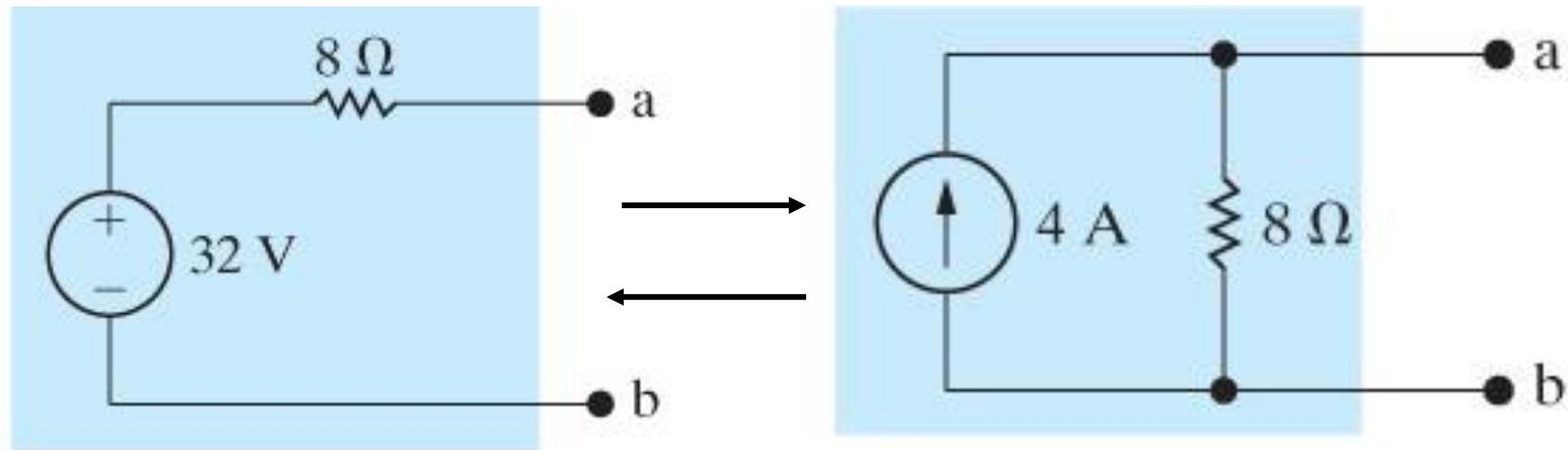


# The Norton Equivalent Circuit

- Get the Norton Equivalent Circuit from the Thevenin by Source Transformation.



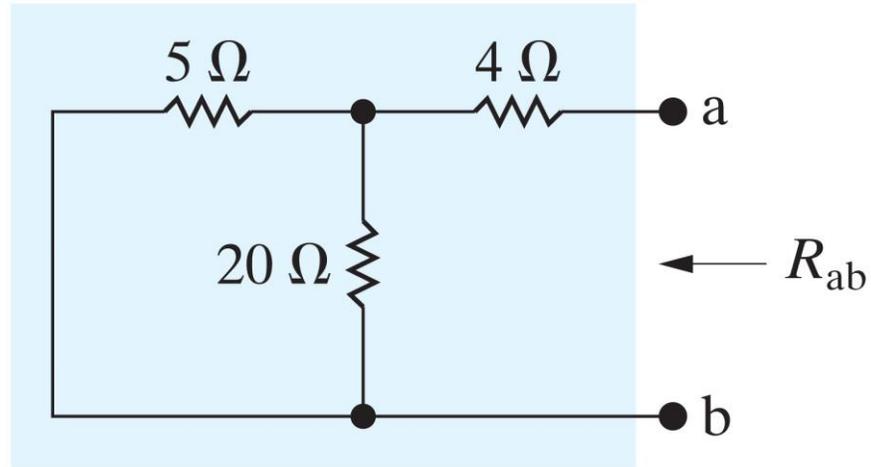
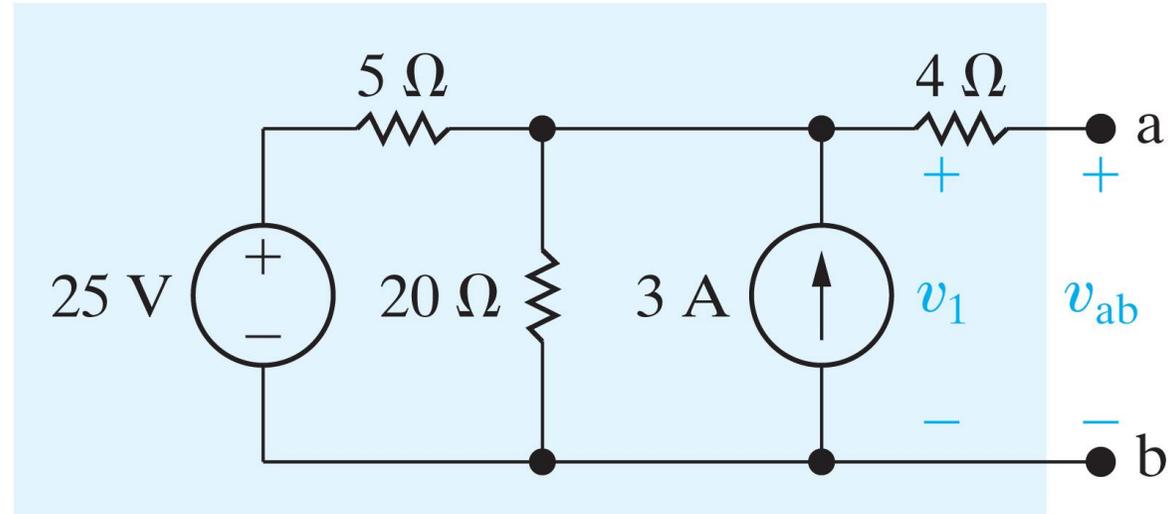
# Alternate Way to Determine the Thevenin Resistance

If the sources are all Independent

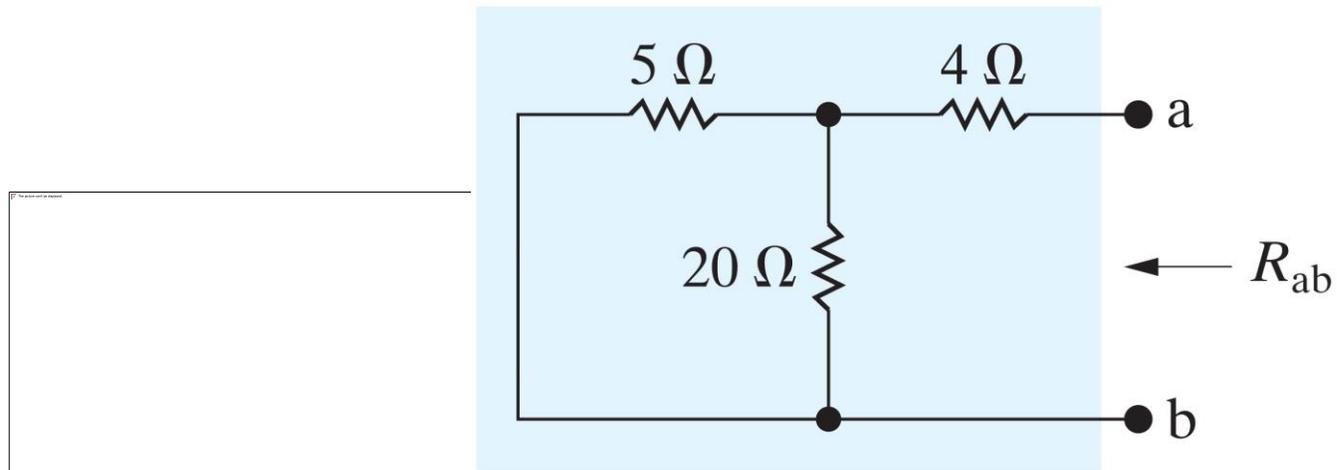
# If the Sources Are All Independent

- Look into the a-b terminals with all sources set equal to 0.
  - Voltage Sources go to Short Circuits
  - Current Sources go to Open Circuits
- Determine the resistance

For our Example



# Looking into the a-b terminals



$$R_{ab} = R_{Th} = 4\Omega + (5\Omega \parallel 20\Omega)$$

$$R_{ab} = R_{Th} = 4 + \frac{(5)(20)}{5 + 20} = 8\Omega$$

# APPLICATION OF THE LAPLACE TRANSFORM TO CIRCUIT ANALYSIS

## LEARNING GOALS

**Laplace circuit solutions**

Showing the usefulness of the Laplace transform

**Circuit Element Models**

Transforming circuits into the Laplace domain

**Analysis Techniques**

All standard analysis techniques, KVL, KCL, node, loop analysis, Thevenin's theorem are applicable

**Transfer Function**

The concept is revisited and given a formal meaning

**Pole-Zero Plots/Bode Plots**

Establishing the connection between them

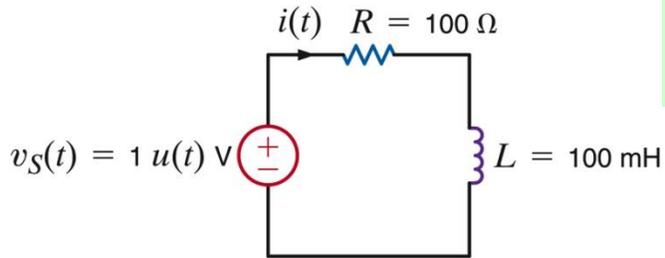
**Steady State Response**

AC analysis revisited



# LAPLACE CIRCUIT SOLUTIONS

We compare a conventional approach to solve differential equations with a technique using the Laplace transform



KVL:  $v_S(t) = Ri(t) + L \frac{di}{dt}(t)$

Complementary equation

$$Ri_C(t) + L \frac{di_C}{dt}(t) = 0 \Rightarrow i_C(t) = K_C e^{-\alpha t}$$

$$RK_C e^{-\alpha t} + LK_C (-\alpha e^{-\alpha t}) = 0 \Rightarrow \alpha = \frac{R}{L}$$

Particular solution for this case

$$i_p(t) = K_p \Rightarrow v_S = 1 = RK_p$$

Use boundary conditions  $v_S(t) = 0$  for  $t < 0 \Rightarrow i(0) = 0$

$$i(t) = \frac{1}{R} + K_C e^{-\frac{R}{L}t}$$

$$i(t) = \frac{1}{R} \left( 1 - e^{-\frac{R}{L}t} \right); t > 0$$

Complementary

$$i = i_C + i_p$$

P  
a  
r  
t  
i  
c  
u  
l  
a  
r

“Take Laplace transform” of the equation

$$v_S(t) = Ri(t) + L \frac{di}{dt}(t)$$

$$V_S(s) = RI(s) + L \mathcal{L} \left[ \frac{di}{dt} \right]$$

$$\mathcal{L} \left[ \frac{di}{dt} \right] = sI(s) - i(0) = sI(s)$$

Q

Initial conditions are automatically included

$$\therefore \frac{1}{s} = RI(s) + LsI(s)$$

$$I(s) = \frac{1}{s(R + Ls)}$$

$$I(s) = \frac{1/L}{s(R/L + s)} = \frac{K_1}{s} + \frac{K_2}{s + R/L}$$

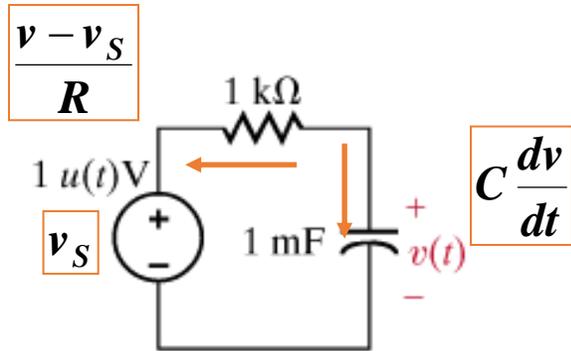
Only algebra is needed

$$K_1 = sI(s) |_{s=0} = \frac{1}{R}$$

$$K_2 = (s + R/L)I(s) |_{s=-R/L} = -\frac{1}{R}$$

No need to search for particular or complementary solutions

$$i(t) = \frac{1}{R} \left( 1 - e^{-\frac{R}{L}t} \right); t > 0$$

**LEARNING BY DOING**Find  $v(t), t > 0$ 

Model using KCL

$$C \frac{dv}{dt} + \frac{v - v_S}{R} = 0$$

$$RC \frac{dv}{dt} + v = v_S$$

$$RC \mathcal{L} \left[ \frac{dv}{dt} \right] + V(s) = V_S(s)$$

$$\mathcal{L} \left[ \frac{dv}{dt} \right] = sV(s) - v(0) = sV(s)$$

$$v_S(t) = 0, t < 0 \Rightarrow v(0) = 0$$

$$v_S = u(t) \Rightarrow V_S(s) = \frac{1}{s}$$

Initial condition given in implicit form

In the Laplace domain the differential equation is now an algebraic equation

$$RCsV(s) + V(s) = \frac{1}{s}$$

$$V(s) = \frac{1}{s(RCs + 1)} = \frac{1/RC}{s(s + 1/RC)}$$

Use partial fractions to determine inverse

$$V(s) = \frac{1/RC}{s(s + 1/RC)} = \frac{K_1}{s} + \frac{K_2}{s + 1/RC}$$

$$K_1 = sV(s) \big|_{s=0} = 1$$

$$K_2 = (s + 1/RC)V(s) \big|_{s=-1/RC} = -1$$

$$v(t) = 1 - e^{-\frac{t}{RC}}, t \geq 0$$

# CIRCUIT ELEMENT MODELS

The method used so far follows the steps:

1. Write the differential equation model
2. Use Laplace transform to convert the model to an algebraic form

For a more efficient approach:

1. Develop s-domain models for circuit elements
2. Draw the “Laplace equivalent circuit” keeping the interconnections and replacing the elements by their s-domain models
3. Analyze the Laplace equivalent circuit. All usual circuit tools are applicable and all equations are algebraic.

Independent sources

$$v_S(t) \rightarrow V_S(s)$$

$$i_S(t) \rightarrow I_S(s)$$

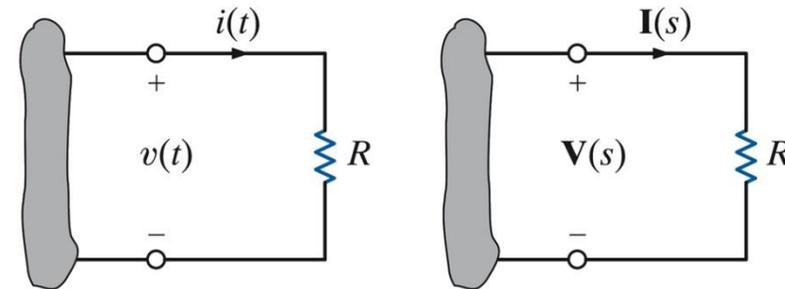
Dependent sources

$$v_D(t) = A i_C(t) \rightarrow V_D(s) = A I_C(s)$$

$$i_D(t) = B v_C(t) \rightarrow I_D(s) = B V_C(s)$$

...

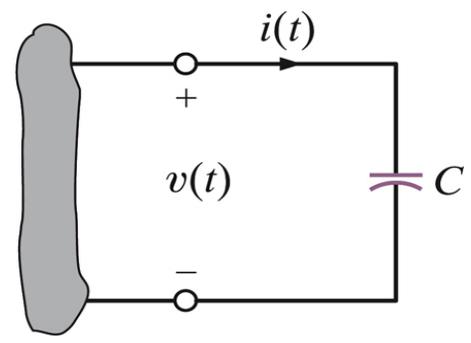
Resistor



$$v(t) = Ri(t) \Rightarrow V(s) = RI(s)$$

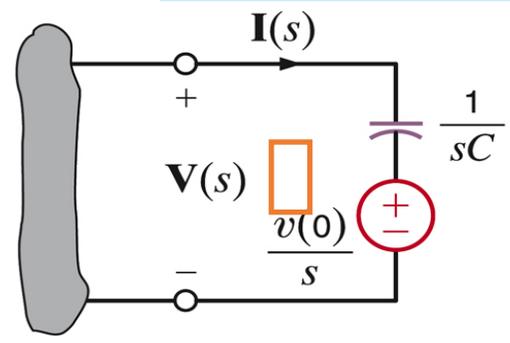


**Capacitor: Model 1**



$$v(t) = \frac{1}{C} \int_0^t i(x) dx + v(0)$$

**Source transformation**



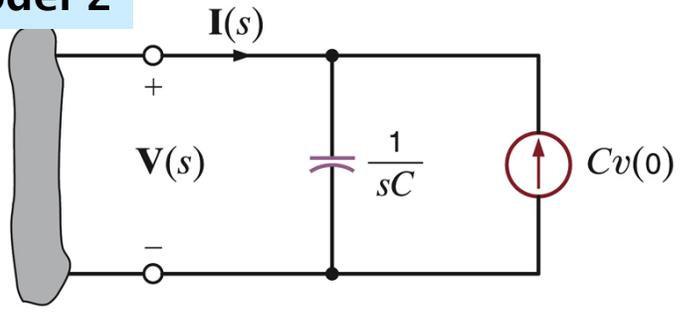
$$V(s) = \frac{1}{Cs} I(s) + \frac{v(0)}{s}$$

$$\mathcal{L} \left[ \int_0^t i(x) dx \right] = \frac{I(s)}{s}$$

$$I_{eq} = \frac{v(0)}{\frac{1}{Cs}} = Cv(0)$$

**Impedance in series with voltage source**

**Capacitor: Model 2**



$$I(s) = CsV(s) - Cv(0)$$

**Impedance in parallel with current source**

